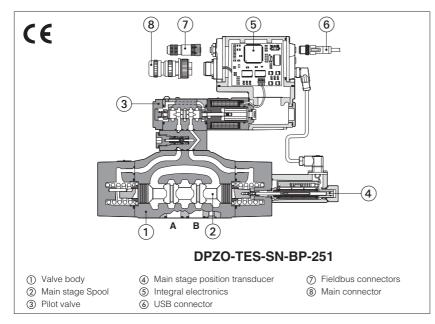


# Two stage proportional directional valves

digital, with position transducers and positive spool overlap



#### **DPZO-TEB. DPZO-TES**

Two stage digital proportional valves specifically designed for directional and speed controls.

They are equipped with main stage LVDT position transducer and positive spool overlap for best dynamics in directional controls and not compensated flow regulations.

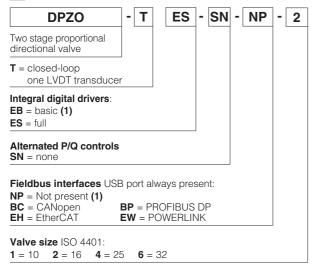
The integral digital electronic driver performs the valve's hydraulic regulation according to the reference signal and assures valve-to-valve interchangeability thanks to the factory presetting.

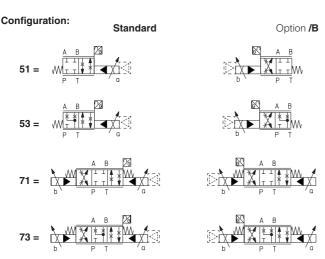
The valves are available in TEB basic execution with analog reference signals and USB port for software functional parameters setting or in TES full execution which includes also optional fieldbus interfaces for functional parameters setting, reference signals and real-time diagnostics.

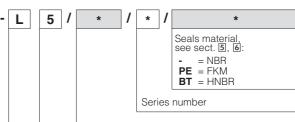
Size: 10 to 32

Max flow: **180** to **1600 l/min** Max pressure: **350 bar** 

#### 1 MODEL CODE for STANDARD SPOOLS







#### Hydraulic options, see section 9:

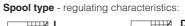
- **B** = solenoid, integral electronics and position transducer at side of port A of the main stage
- **D** = internal drain
- $\mathbf{E}$  = external pilot (through port X)

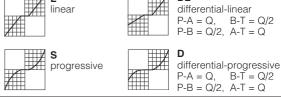
#### Electronic options, see sections 11

- I = current reference input and monitor 4÷20 mA (omit for standard voltage reference input and monitor ±10 V)
- **F** = fault signal
- **Q** = enable signal
- **Z** = double power supply **(2)**, enable, fault and monitor signals (12 pin connector)

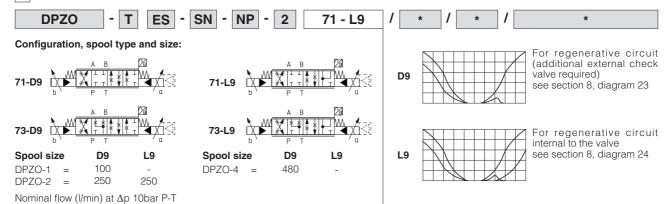
| Spool size | <b>3</b> (L,S,D) | <b>5</b> (L,DL,S,D) | <b>5</b> (L,S,D) |
|------------|------------------|---------------------|------------------|
| DPZO-1 =   | -                | 100                 | -                |
| DPZO-2 =   | 160              | 250                 | -                |
| DPZO-4 =   | -                | 480                 | -                |
| DPZO-6 =   | -                | -                   | 640              |
|            |                  | 101 D.T             |                  |

Nominal flow (I/min) at Δp 10bar P-T





#### **MODEL CODE for SPECIAL SPOOLS -** refer to section ① for valve model code and options



#### 3 GENERAL NOTES

DPZO-TEB, TES proportional valves are CE marked according to the applicable Directives (e.g. Immunity/Emission EMC Directive and Low Voltage Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in table F003 and in the installation notes supplied with relevant components. The electrical signals of the valve (e.g. monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-982).

# WARNING

To avoid overheating and possible damage of the electronic driver, the valves must be never energized without hydraulic supply to the pilot stage. In case of prolonged pauses of the valve operation during the machine cycle, it is always advisable to disable the driver (option /Q or /Z). A safety fuse 2,5 A installed on 24VDc power supply of each valve is always recommended, see also Power supply note at sections [1]

#### 4 FIELDBUS - only for TES

Fieldbus allows the direct communication of the proportional valve with machine control unit for digital reference signal, diagnostics and settings of functional parameters. Analog reference signal remain available on the main connector for quick commissioning and maintenance. For detailed information about fieldbus features and specification see tech table **GS510**.

#### 5 MAIN CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

| Any position  |  |   |  |  |
|---|--|---|--|--|
| Roughness index, Ra 0,4 flatness ratio 0,01/100 (ISO 1101)  |  |   |  |  |
| 75 years, see technical   | table P007   |   |  |  |
|   |  |   |  |  |
|   |  |   |  |  |
| 3 ÷ 3,3 Ω   |  |   |  |  |
| 2,6 A   |  |   |  |  |
| 50 Watt   |  |   |  |  |
| H (180°) Due to the occurring surface temperatures of the solenoid coils, the European standards ISO 13732-1 and EN982 must be taken into account |  |   |  |  |
| IP66/67 with mating cor   | nnector  |   |  |  |
| Tropical coating on elec  | ctronics PCB   |   |  |  |
| Continuous rating (ED=  | 100%)  |   |  |  |
| See technical table G004  |  |   |  |  |
| USB<br>Atos ASCII coding  | CANopen<br>EN50325-4 + DS408   | PROFIBUS DP<br>EN50170-2/IEC61158   | EtherCAT, POWERLINK IEC 61158  |  |
| not insulated<br>USB 2.0 + USB OTG  | optical insulated<br>CAN ISO11898  | optical insulated<br>RS485  | Fast Ethernet, insulated 100 Base TX   |  |
|   | Roughness index, Ra 0 75 years, see technical standard execution = -2 /BT option = -40°C ÷ +6 Standard execution = -2 /BT option = -40°C ÷ +7 3 ÷ 3,3 Ω 2,6 A 50 Watt H (180°) Due to the occ ISO 13732-1 and EN98 IP66/67 with mating cor Tropical coating on electorinuous rating (ED= See technical table G00 USB Atos ASCII coding not insulated | Roughness index, Ra 0,4 flatness ratio 0,01/100 75 years, see technical table P007 standard execution = -20°C ÷ +60°C /BT option = -40°C ÷ +60°C Standard execution = -20°C ÷ +70°C /BT option = -40°C ÷ +70°C 3 ÷ 3,3 Ω 2,6 A 50 Watt H (180°) Due to the occuring surface temperatu ISO 13732-1 and EN982 must be taken into acc IP66/67 with mating connector Tropical coating on electronics PCB Continuous rating (ED=100%) See technical table G004 USB Atos ASCII coding CANopen EN50325-4 + DS408 not insulated | Roughness index, Ra 0,4 flatness ratio 0,01/100 (ISO 1101) 75 years, see technical table P007 standard execution = -20°C ÷ +60°C //BT option = -40°C ÷ +60°C //BT option = -40°C ÷ +70°C //BT option = -40°C ÷ +60°C //BT option = -40°C ÷ +70°C //BT option |  |

| Valve model                            |                             | DPZO-*-1  | DPZO-*-2   |         | DPZO-*-4 | DPZO-*-6   |  |
|--|-----------------------------|---|--|---------|----------|------------|--|
| Pressure limits                        | [bar]                       | p   | ports <b>P</b> , <b>A</b> , <b>B</b> , <b>X</b> = 350; <b>T</b> = 250 (10 for option /D); <b>Y</b> = 10; |         |          |            |  |
| Spool type                             | standard                    | L5, DL5, S5, D5   | L3, S3, D3   | L5, DL5 | , S5, D5 | L5, S5, D5 |  |
|  | special                     | D9  |  | D9, L9  | D9       |            |  |
| Nominal flow                           | [l/min]                     |   |  |         |          |            |  |
| (1)                                    | $\Delta p = 10 \text{ bar}$ | 100   | 160  | 250     | 480      | 640        |  |
| Δp P-T                                 | Δp = 30 bar                 | 160   | 270  | 430     | 830      | 1100       |  |
| Max permissible flow                   | [l/min]                     | 180   | 400  | 550     | 1000     | 1600       |  |
| Piloting pressure [bar]                |                             | min. = 25; max = 350 (option /G advisable for pilot pressure > 200 bar) |  |         |          |            |  |
| Piloting volume                        | [cm <sup>3</sup> ]          | 1,4   | 3  | ,7      | 9,0      | 21,6       |  |
| Piloting flow (2)                      | [l/min]                     | 1,7   | 3  | 5,7     | 6,8      | 14,4       |  |
| Leakage                                | Pilot [cm³]                 | 100/300   | 100  | /300    | 200/500  | 900/2800   |  |
| (3)                                    | Main stage [I/min]          | 0,15/0,5  | 0,2  | /0,6    | 0,3/1,0  | 1,0/3,0    |  |
| Response time (0-100% step signal) (4) | [ms]                        | < 60  | < 75   |         | < 80     | < 120      |  |
| Hysteresis                             |                             | ≤ 0,1 [% of max regulation]   |  |         |          |            |  |
| Repeatability                          |                             | ± 0,1 [% of max regulation]   |  |         |          |            |  |
| Thermal drift                          |                             | zero point displacement < 1% at ΔT = 40°C                               |  |         |          |            |  |

#### Notes:

above performance data refer to valves coupled with Atos electronic drivers, see section **a**.

## 6 SEALS AND HYDRAULIC FLUID - for other fluids not included in below table, consult our technical office

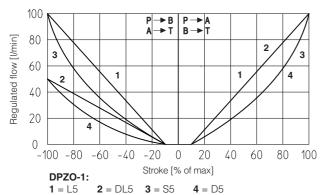
| Seals, recommended fluid temperature | NBR seals (standard) = $-20^{\circ}$ C ÷ $+60^{\circ}$ C, with HFC hydraulic fluids = $-20^{\circ}$ C ÷ $+50^{\circ}$ C FKM seals (/PE option) = $-20^{\circ}$ C ÷ $+80^{\circ}$ C HNBR seals (/BT option) = $-40^{\circ}$ C ÷ $+60^{\circ}$ C, with HFC hydraulic fluids = $-40^{\circ}$ C ÷ $+50^{\circ}$ C |   |               |  |  |
|--------------------------------------|---|---|---------------|--|--|
| Recommended viscosity                | 20÷100 mm²/s - max allowed r  | 20÷100 mm²/s - max allowed range 15 ÷ 380 mm²/s |               |  |  |
| Fluid contamination class            | ISO 4406 class 20/18/15 NAS 1638 class 9, in line filters of 10 μm (β10 ≥75 recommended)  |   |               |  |  |
| Hydraulic fluid                      | Suitable seals type   | Classification                                  | Ref. Standard |  |  |
| Mineral oils                         | NBR, FKM, HNBR  | HL, HLP, HLPD, HVLP, HVLPD                      | DIN 51524     |  |  |
| Flame resistant without water        | FKM   | HFDU, HFDR                                      | ISO 12922     |  |  |
| Flame resistant with water           | NBR, HNBR   | HFC   | 100 12922     |  |  |

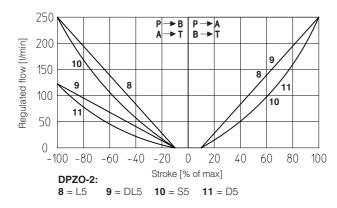
#### 7 ELECTRONIC DRIVERS - for main and communication connector see sections [13], [14]

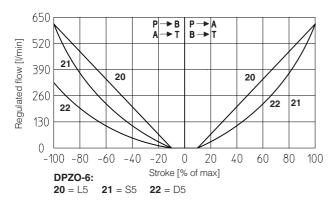
| Valve model   | TEB                   | TES   |  |
|---------------|-----------------------|-------|--|
| Drivers model | E-RI-TEB-N E-RI-TES-N |       |  |
| Туре          | Dig                   | jital |  |
| Format        | Integral to valve     |       |  |
| Data sheet    | GS208                 | GS210 |  |

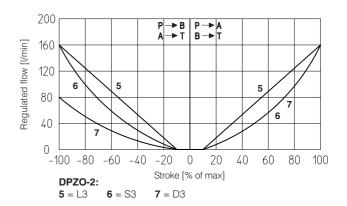
## 8 DIAGRAMS (based on mineral oil ISO VG 46 at 50 °C)

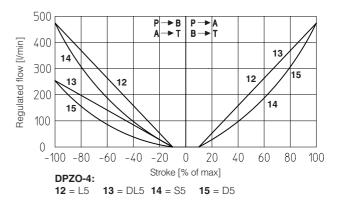
#### 8.1 Regulation diagrams (values measure at Δp 10 bar P-T)









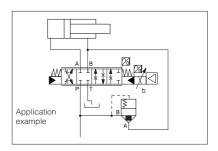


#### Note:

Hydraulic configuration vs. reference signal (standard and option /B) Reference signal  $\begin{smallmatrix}0&\div+10&V\\12&\div&20\text{ mA}\end{smallmatrix}$  } P  $\rightarrow$  A / B  $\rightarrow$  T

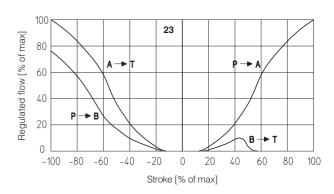
23 = differential - regenerative spool D9 (not available for valve size 32 and 35)

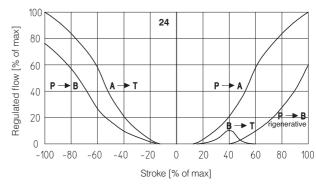
D9 spool type with a fourth position specific to regenerative circuit, performed by means of an additional external check



24 = linear - internal regenerative spool L9 (available only for valve size 16)

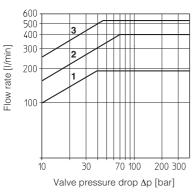
L9 spool type with a fourth position specific to perform a regenerative circuit internal to the valve.

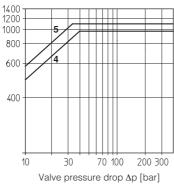


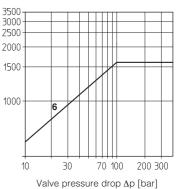


#### 8.2 Operating diagrams

Flow /\Dp diagram stated at 100% of spool stroke







#### DPZO-1:

1 = spools L5, S5, D5, DL5, D9

#### DPZO-2:

2 = spools L3, S3, D3

**3** = spools L5, S5, D5, DL5, D9, L9

#### DPZO-4:

4 = spools L5, S5, D5, DL5, D9

#### DPZO-4M:

**5** = spools L5, S5, D5, DL5, D9

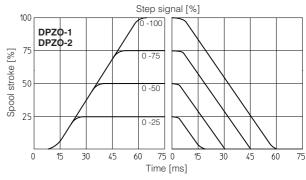
#### DPZO-6:

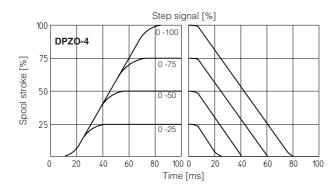
6 = L5, S5, D5

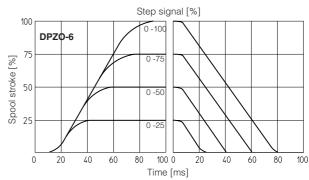
#### 8.3 Response time

The response times in below diagrams are measured at different steps of the reference input signal. They have to be considered as average values.

For the valves with digital electronics the dynamics performances can be optimized by setting the internal software parame-







#### 9 HYDRAULIC OPTIONS

#### 9.1 Option /B

Solenoid, integral electronics and position transducer at side of port A of the main stage. For hydraulic configuration vs reference signal, see section 8.1

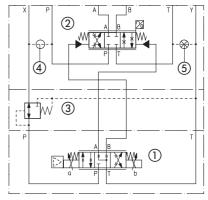
#### 9.2 Pilot and drain configuration

The pilot / drain configuration can be modified as shown in the functional scheme here aside, for detailed view of plugs position, see section [15]

The valve's standard configuration provides internal pilot and external drain.

For different pilot / drain configuration select: **Option /E** External pilot (through port X) **Option /D** Internal drain (through port T)

# **FUNCTIONAL SCHEME** example of configuration 71



- Pilot valve
- ② Main stage
- 3 Pressure reducing valve
- 4) Plug to be added for external pilot trough port X
- (5) Plug to be removed for internal drain through port T

#### 10 ELECTRONIC OPTIONS

Standard driver execution provides on the 7 pin main connector:

Power supply

- 24 VDc must be appropriately stabilized or rectified and filtered; **2,5 A** fuse is time lag required in series to each driver power supply. Apply at least a 10000  $\mu$ F/40 V capacitance to single phase rectifiers or a 4700  $\mu$ F/40 V capacitance to three phase rectifiers

Reference input signal - analog differential input with ±10 VDC nominal range (pin D, E), proportional to desired valve spool position

Monitor output signal - analog output signal proportional to the actual valve's spool position with ±10VDC nominal range

**Note:** a minimum booting time between 400 and 800 ms has be considered from the driver energizing with the 24 Vpc power supply before the valve has been ready to operate. During this time the current to the valve coils is switched to zero.

#### 10.1 Option /F

It provides a Fault output signal in place of the Monitor output signal, to indicate fault conditions of the driver (cable interruption of spool transducers or reference signal - for /I option): Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC

#### 10.2 Option /I

It provides  $4 \div 20$  mA current reference and monitor signals, instead of the standard  $\pm 10$  V.

Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 V or ±20 mA.

It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

#### 10.3 Option /Q

It provides the possibility to enable or disable the valve functioning without cutting the power supply (the valve functioning is disabled but the driver current output stage is still active). To enable the driver supply a 24 VDC on the enable input signal.

#### 10.4 Option /Z

It provides, on the 12 pin main connector, the following additional features:

#### **Enable Input Signal**

To enable the driver, supply 24 VDC on pin 3 referred to pin 2: when the Enable signal is set to zero the valve functioning is disabled (zero current to the solenoid) but the driver current output stage is still active.

#### Fault Output Signal

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4÷20mA input, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24VDC (pin 11 referred to pin 2): Fault status is not affected by the Enable input signal

#### Power supply for driver's logics and communication - only for TES

Separated power supply for the solenoid (pin 1, 2) and for the digital electronic circuits (pin 9, 10).

Cutting solenoid power supply allows to interrupt the valve functioning but keeping energized the digital electronics thus avoiding fault conditions of the machine fieldbus controller. This condition aids to realize safety systems in compliance with European Norms EN13849-1 (ex EN954-1).

#### 10.5 Possible combined options

/FI, /IQ and /IZ

## 11 ELECTRONIC CONNECTIONS AND LEDS

## 11.1 Main connector signal - 7 pin - standard, /F and /Q options $\bigcirc$

| PIN | Standard       | /Q           | /F    | TECHNICAL SPECIFICATIONS                                      | NOTES                  |
|-----|----------------|--------------|-------|---|------------------------|
| А   | V+             |              |       | Power supply 24 Vpc   | Input - power supply   |
| В   | V0             |              |       | Power supply 0 Vpc  | Gnd - power supply     |
|     | AGND           |              | AGND  | Analog ground   | Gnd - analog signal    |
|     |                | ENABLE       |       | Enable (24 VDC) or disable (0 VDC) the valve, referred to V0  | Input - on/off signal  |
|     | Q_INPUT+       |              |       | Flow reference input signal: ±10 Vpc / ±20 mA maximum range   | Input - analog signal  |
|     |                |              |       | Defaults are ±10 Vpc for standard and 4 ÷ 20 mA for /I option | Software selectable    |
| Е   | INPUT-         |              |       | Negative reference input signal for Q_INPUT+                  | Input - analog signal  |
|     | Q_MONITOR      | referred to: |       | Flow monitor output signal: ±10 Vpc / ±20 mA maximum range    | Output - analog signal |
| F   | AGND           | V0           |       | Defaults are ±10 Vpc for standard and 4 ÷ 20 mA for /I option | Software selectable    |
|     |                |              | FAULT | Fault (0 Vpc) or normal working (24 Vpc)                      | Output - on/off signal |
| G   | G <b>EARTH</b> |              |       | Internally connected to the driver housing                    |                        |

#### 11.2 Main connector signal - 12 pin - /Z option (A2)

| PIN      | TEB-SN /Z                 | TES-SN /Z        | TECHNICAL SPECIFICATIONS  | NOTES                                     |
|----------|---------------------------|------------------|---|---|
|          | V+                        |                  | Power supply 24 Vpc   | Input - power supply                      |
| 1        | V0                        |                  | Power supply 0 Vpc  | Gnd - power supply                        |
| 2        | ENABLE refe<br>V0         | erred to:<br>VL0 | Enable (24 Vpc) or disable (0 Vpc) the valve  | Input - on/off signal                     |
| 4        | Q_INPUT+                  |                  | Flow reference input signal: ±10 Vpc / ±20 mA maximum range Defaults are ±10 Vpc for standard and 4 ÷ 20 mA for /I option | Input - analog signal Software selectable |
| 5        | INPUT-                    |                  | Negative reference input signal for Q_INPUT+  | Input - analog signal                     |
| 6        | Q_MONITOR referred to:    |                  | Flow monitor output signal: ±10 Vpc / ±20 mA maximum range  | Input - analog signal Software selectable |
| 7        | AGND<br>AGND              | VL0              | Defaults are ±10 Vpc for standard and 4 ÷ 20 mA for /I option  Analog ground  | Output - analog signal                    |
|          | R ENABLE                  | NC               | Do not connect  Repeat enable, output repeter signal of enable input, referred to V0                                      | Gnd - analog signal                       |
| 8        |                           | NC               | Do not connect  | Output - on/off signal                    |
| 9        | NC                        | VL+              | Do not connect  Power supply 24 Vbc for driver's logic and communication  | Input - power supply                      |
| 10       | NC                        |                  | Do not connect  |   |
|          |                           | VL0              | Power supply 0 Vpc for driver's logic and communication   | Gnd - power supply                        |
| 11<br>PE | FAULT referred to: V0 VL0 |                  | Fault (0 Vpc) or normal working (24 Vpc)  | Output - on/off signal                    |
|          | EARTH                     |                  | Internally connected to the driver housing  |   |

 $\textbf{Note:} \ \text{do not disconnect VL0 before VL+} \ \text{when the driver is connected to PC USB port}$ 

## 

|     | B USB connector - M12 - 5 pin always present |                                     |  |  |  |  |  |  |
|-----|--|-------------------------------------|--|--|--|--|--|--|
| PIN | PIN SIGNAL TECHNICAL SPECIFICATION (1)       |                                     |  |  |  |  |  |  |
| 1   | +5V_USB                                      | Supply for external USB Flash Drive |  |  |  |  |  |  |
| 2   | ID USB Flash Drive identification            |                                     |  |  |  |  |  |  |
| 3   | 3 GND_USB Signal zero data line              |                                     |  |  |  |  |  |  |
| 4   | 4 <b>D-</b> Data line -                      |                                     |  |  |  |  |  |  |
| 5   | D+   | Data line +                         |  |  |  |  |  |  |

| (C1) (                                    | ©1 ©2 BP fieldbus execution, connector - M12 - 5 pin |                                       |  |  |  |  |  |
|---|--|---------------------------------------|--|--|--|--|--|
| PIN SIGNAL TECHNICAL SPECIFICATION (1)    |  |                                       |  |  |  |  |  |
| 1   | +5V  | Termination supply signal             |  |  |  |  |  |
| 2 LINE-A Bus line (high)                  |  |                                       |  |  |  |  |  |
| 3 <b>DGND</b> Data line and termination s |  | Data line and termination signal zero |  |  |  |  |  |
| 4 LINE-B Bus line (low)                   |  |                                       |  |  |  |  |  |
| 5 SHIELD                                  |  |                                       |  |  |  |  |  |

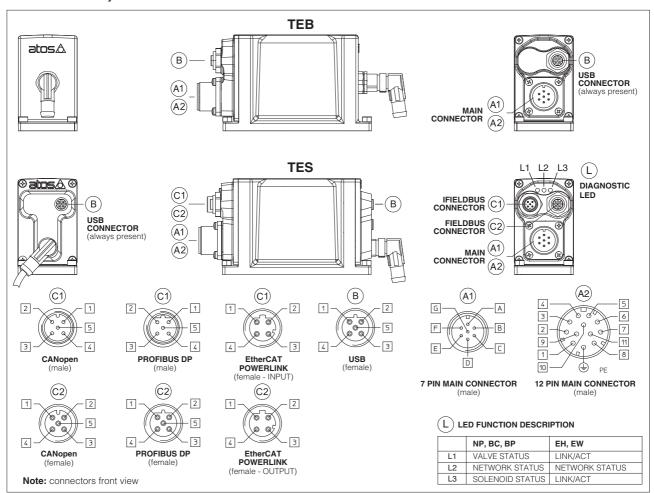
 $\textbf{Notes: (1)} \ \text{shield connection on connector's housing is recommended} \\$ 

| (C1) ( | ©1) ©2) BC fieldbus execution, connector - M12 - 5 pin |                                   |  |  |  |  |  |
|--------|--|-----------------------------------|--|--|--|--|--|
| PIN    | SIGNAL   | TECHNICAL SPECIFICATION (1)       |  |  |  |  |  |
| 1      | CAN_SHLD   | Shield                            |  |  |  |  |  |
| 2      | not used   | ©1-©2 pass-through connection (2) |  |  |  |  |  |
| 3      | CAN_GND Signal zero data line                          |                                   |  |  |  |  |  |
| 4      | CAN_H  | Bus line (high)                   |  |  |  |  |  |
| 5      | CAN_L  | Bus line (low)                    |  |  |  |  |  |

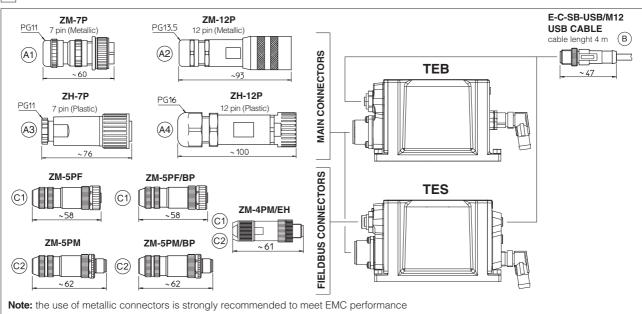
| (c1) (  | © EH, EW fieldbus execution,connector - M12 - 4 pin |                             |  |  |  |  |  |
|---------|---|-----------------------------|--|--|--|--|--|
| PIN     | SIGNAL  | TECHNICAL SPECIFICATION (1) |  |  |  |  |  |
| 1       | TX+   | Transmitter                 |  |  |  |  |  |
| 2       | RX+   | Receiver                    |  |  |  |  |  |
| 3       | TX-   | Transmitter                 |  |  |  |  |  |
| 4       | RX-   | Receiver                    |  |  |  |  |  |
| Housing | SHIELD  |                             |  |  |  |  |  |

(2): pin 2 can be fed with external +5V supply of CAN interface

#### 11.4 Connections layout



#### 11 CONNECTORS



#### MODEL CODES OF MAIN CONNECTORS AND COMMUNICATION CONNECTORS - to be ordered separately

| VALVE VERSION     | TEB<br>TES | TEB /Z<br>TES /Z | BC - CANopen       | BP - PROFIBUS DP | EH - EtherCat<br>EW - POWERLINK |
|-------------------|------------|------------------|--------------------|------------------|---------------------------------|
| CONNECTOR CODE    | ZM-7P (A1) | ZM-12P (A2)      | ZM-5PF C1          | ZM-5PF/BP ©1     | ZM-4PM/E ©1                     |
| CONNECTOR CODE    | ZH-7P (A3) | ZH-12P (A4)      | ZM-5PM ©2          | ZM-5PM/BP ©2     | ZM-4PM/E ©2                     |
| PROTECTION DEGREE |            |                  | IP67               |                  |                                 |
| DATA SHEET        |            |                  | GS208, GS210, K500 |                  |                                 |

#### 14 PROGRAMMING TOOLS - see table GS500

Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via USB port to the digital driver. For fieldbus versions, the software permits valve's parameterization through USB port also if the driver is connected to the central machine unit via fieldbus.

The software is available in different versions according to the driver's options:

E-SW-BASIC NP (USB) support: PS (Serial) IR (Infrared) BC (CANopen) E-SW-FIELDBUS support: BP (PROFIBUS DP) EH (EtherCAT)

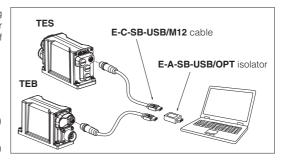
EW (POWERLINK)

E-SW-\*/PQ valves with SP, SF, SL alternated control (e.g. E-SW-BASIC/PQ) support:

WARNING: drivers USB port is not isolated!

The use of isolator adapter is highly recommended for PC protection (see table GS500)

#### **USB** connection

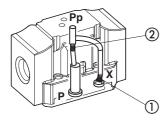


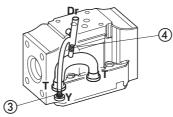
#### 15 PLUGS LOCATION FOR PILOT/DRAIN CHANNELS

Depending on the position of internal plugs, different pilot/drain configurations can be obtained as shown below. To modify the pilot/drain configuration, proper plugs must only be interchanged. The plugs have to be sealed using loctite 270. Standard valves configuration provides internal pilot and external drain

DPZO-1

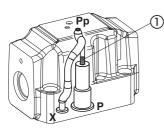
#### Pilot channels Drain channels

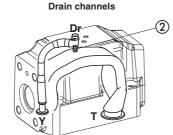




Internal piloting: blinded plug SP-X300F ① in X; External piloting: blinded plug SP-X300F (2) in Pp; Internal drain: blinded plug SP-X300F (3) in Y; External drain: blinded plug SP-X300F (4) in Dr.

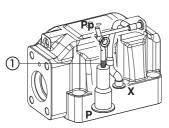
#### DPZO-2 Pilot channels

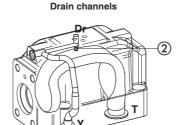




Internal piloting: Without blinded plug SP-X300F ①; External piloting: Add blinded plug SP-X300F ①; Without blinded plug SP-X300F 2; Internal drain: **External drain:** Add blinded plug SP-X300F ②.

#### DPZO-4 Pilot channels





Drain channels

Internal piloting: Without blinded plug SP-X500F ①; External piloting: Add blinded plug SP-X500F ①; Without blinded plug SP-X300F 2: Internal drain: External drain: Add blinded plug SP-X300F 2.

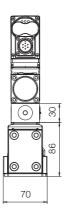
#### DPZO-6 Pilot channels

# 3 (1)

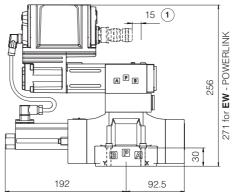
Internal piloting: Without plug ①;

External piloting: Add DIN-908 M16x1,5 in pos ①; Without blinded plug SP-X300F 3; Internal drain: External drain: Add blinded plug SP-X300F 3.





#### **DPZO-TEB-\*-15\* DPZO-TES-\*-15\***



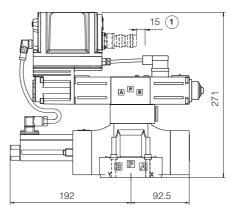
Mass 9 kg

#### **DPZO-TEB-\*-17\* DPZO-TES-\*-17\***

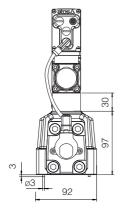
#### ISO 4401: 2005

#### Mounting surface: 4401-05-05-0-05

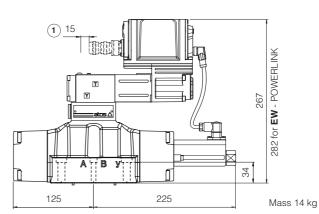
(see table P005) Fastening bolts: 4 socket head screws M6x40 class 12.9 Tightening torque = 15 Nm Seals: 5 OR 2050; 2 OR 108 Diameter of ports A, B, P, T:  $\emptyset$  = 11 mm; Diameter of ports X, Y:  $\emptyset = 5$  mm;



Mass 9,8 kg



#### **DPZO-TEB-\*-25\* DPZO-TES-\*-25\***

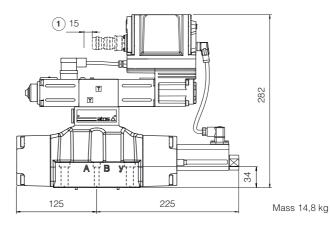


#### **DPZO-TEB-\*-27\* DPZO-TES-\*-27\***

#### ISO 4401: 2005

## Mounting surface: 4401-07-07-0-05

(see table P005) Fastening bolts: 4 socket head screws M10x50 class 12.9 Tightening torque = 70 Nm 2 socket head screws M6x45 class 12.9 Tightening torque = 15 Nm Seals: 4 OR 130; 2 OR 2043 Diameter of ports A, B, P, T: Ø = 20 mm; Diameter of ports X, Y:  $\emptyset = 7$  mm;



#### 1 = Space to remove the 7 or 12 pin main connector

For main and communication connectors see section 13, 14



